# EXACT SOLUTIONS OF SUPERSYMMETRIC NONLINEAR SCHRÖDINGER EQUATIONS AND COUPLED K-dV EQUATIONS 

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In this communication we report certain types of exact solutions of supersymmetric nonlinear Schrödinger equations and coupled KdV-equations by making an ansatz for the solution in each case.

## 1. Introduction

During the last two decades, study of the nonlinear wave phenomena has made a remarkable stride (Scott et al. [1]). It has been confirmed that several nonlinear partial differential equations are widely applicable to the various nonlinear phenomena in physics. One must solve nonlinear equations to get a knowledge of the system but the methods of solving are very few up to this time. Each of the methods, viz., Inverse scattering method (Gardner et al. [2]), Hirota's method (Hirota [3]), Trace method (Wadati and Sawada [4]) and direct algebraic method (Hereman et al. [5]) has some constraints. Here we present certain type of exact solutions of supersymmetric nonlinear Schrödinger equation (NLSE, Kulish [6]) and of coupled K-dV equation (Hirota and Satsuma [7]) by making an ansatz for the solution in each case following the method suggested by Huibin and Kelin (Huibin and Kelin [8,9]).

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## 2. Formulation

The supersymmetric NLSE's (Kulish [6]) read as:

$$
\begin{align*}
i q_{t} & =-q_{x x}+2 k q^{+} q^{2}+k \Psi \Psi^{+}-i \sqrt{k} \Psi \Psi_{x}  \tag{1a}\\
i \Psi_{t} & =-2 \Psi_{x x}+k q^{+} q-i \sqrt{k}\left(2 q \Psi_{x}^{+}+\Psi^{+} q_{x}\right) \tag{1b}
\end{align*}
$$

where $q(x, t)$ is the original field and $\Psi(x, t), \Psi^{+}(x, t)$ are the fermionic counterparts introduced through supersymmetry. In the following we will be working with the real and imaginary parts of $(1 a, b)$ and so we set

$$
\begin{align*}
& q=u_{0}+i v_{0}  \tag{2a}\\
& \Psi=u_{1}+i v_{1} \tag{2b}
\end{align*}
$$

whence we have the four nonlinear partial differential equations

$$
\begin{gather*}
u_{0 t}=-v_{0 x x}+k\left[2 v_{0}\left(u_{0}^{2}+v_{0}^{2}\right)+v_{0}\left(u_{1}^{2}+v_{1}^{2}\right)\right]-\sqrt{k}\left[u_{1} u_{1 x}-v_{1} v_{1 x}\right]  \tag{3a}\\
-v_{0 t}=-u_{0 x x}+k\left[2 u_{0}\left(u_{0}^{2}+v_{0}^{2}\right)+u_{0}\left(u_{1}^{2}+v_{1}^{2}\right]+\sqrt{k}\left[v_{1} u_{1 x}-u_{1} v_{1 x}\right]\right.  \tag{3b}\\
-v_{1 t}=-2 u_{1 x x}+k u_{1}\left(u_{0}^{2}+v_{0}^{2}\right)+\sqrt{k}\left[2\left(u_{0} v_{0}-u_{0} v_{1 x}\right)+\left(u_{1} v_{0 x}-v_{1} u_{0 x}\right)\right]  \tag{3c}\\
u_{1 t}=-2 v_{1 x x}+k v_{1}\left(u_{0}^{2}+v_{0}^{2}\right)-\sqrt{k}\left[2\left(u_{0} u_{1 x}+v_{0} v_{1 x}\right)+\left(u_{1} u_{0 x}+v_{1} v_{0 x}\right)\right] \tag{3d}
\end{gather*}
$$

We now look for the travelling wave solutions of $(3 a-d)$ that is, we assume that

$$
\begin{align*}
& u_{0}(x, t)=u_{0}(x-\lambda t)=u_{0}(\xi)  \tag{4a}\\
& v_{0}(x, t)=v_{0}(x-\lambda t)=v_{0}(\xi)  \tag{4b}\\
& u_{1}(x, t)=u_{1}(x-\lambda t)=u_{1}(\xi)  \tag{4c}\\
& v_{1}(x, t)=v_{1}(x-\lambda t)=v_{1}(\xi) \tag{4d}
\end{align*}
$$

where $\lambda$ is velocity to be determined. Inserting (4) into (3), we get

$$
\begin{gather*}
-\lambda u_{0 \xi}=-v_{0 \xi \xi}+k\left[2 v_{0}\left(u_{0}^{2}+v_{0}^{2}\right)+v_{0}\left(u_{1}^{2}+v_{1}^{2}\right)\right]-\sqrt{k}\left[u_{1} u_{1 \xi}-v_{1} v_{1 \xi}\right]  \tag{5a}\\
\lambda v_{0 \xi}=-u_{0 \xi \xi}+k\left[2 u_{0}\left(u_{0}^{2}+v_{0}^{2}\right)+u_{0}\left(u_{1}^{2}+v_{1}^{2}\right)\right]+\sqrt{k}\left[v_{1} u_{1 \xi}+u_{1} v_{1 \xi}\right]  \tag{5b}\\
\lambda v_{1 \xi}=-2 u_{1 \xi \xi}+k u_{1}\left(u_{0}^{2}+v_{0}^{2}\right)+\sqrt{k}\left[2\left(v_{0} u_{1 \xi}-u_{0} v_{1 \xi}\right)+\left(u_{1} v_{0 \xi}-v_{1} u_{0 \xi}\right)\right] \tag{5c}
\end{gather*}
$$

$$
\begin{equation*}
-\lambda u_{1 \xi}=-2 v_{1 \xi \xi}+k v_{1}\left(u_{0}^{2}+v_{0}^{2}\right)-\sqrt{k}\left[2\left(u_{0} u_{1 \xi}+v_{0} v_{1 \xi}\right)+\left(u_{1} u_{0 \xi}+v_{1} v_{0 \xi}\right)\right] . \tag{5d}
\end{equation*}
$$

To the equations $5(\mathrm{a})-(\mathrm{d})$, following the method of Huibin and Kelin $[8,9]$, we make the ansatzs

$$
\begin{array}{ll}
u_{0}=\sum_{i=0}^{m} a_{i}(\tanh \mu)^{i}, & v_{o}=\sum_{i=0}^{m} b_{i}(\tanh \mu)^{i} \\
u_{1}=\sum_{i=0}^{m} c_{i}(\tanh \mu)^{i}, & v_{1}=\sum_{i=0}^{m} d_{i}(\tanh \mu)^{i} \tag{6c,d}
\end{array}
$$

where the integer $m$ and parameters $a_{i}, b_{i}, c_{i}, d_{i}(i=1, \ldots m)$ and $\mu$ are to be determined. The requirement that the highest power of the function $(\tanh \mu \xi)$ for the nonlinear term, say, $v_{0} u_{0}^{2}$ (or $u_{1} u_{1 \xi}$ ) of 5 (a) and that for the derivative term $v_{0 \xi \xi}$ must be equal gives the following relation

$$
\begin{array}{ll}
m+2=3 m & {[\text { or } 2 m+1=3 m} \\
\text { so here, } m=1 & \text { so here } m=1]
\end{array}
$$

For the other equations of the set (5), we obtain $m=1$. So the equations (6) can now be written as

$$
\begin{gather*}
u_{0}=a \tanh (\mu \xi)  \tag{7a}\\
v_{0}=b_{1}+b_{2} \tanh (\mu \xi)  \tag{7b}\\
u_{1}=c \tanh (\mu \xi)  \tag{7c}\\
v_{1}=d_{1}+d_{2} \tanh (\mu \xi) \tag{7d}
\end{gather*}
$$

where $a, b_{1}, b_{2}, c, d_{1}, d_{2}$ and $\mu$ are the parameters to be determined. Here in $u_{0}$ and $u_{1}$, we have dropped the parameters $a_{0}$ and $c_{0}$ and taken $a_{1}=a$ and $c_{1}=c$ in order to avoid complexities. In general, one can incorporate $a_{0}, c_{0}$. Inserting now equations (7) into (5) and equating the same power of $\tanh (\mu \xi)$, we get the following parametric equations

$$
\begin{gather*}
-\lambda a \mu=k\left[2 b_{1}^{3}+b_{1} d_{1}^{2}\right]+\sqrt{k}\left[d_{1} d_{2}\right] \mu  \tag{8a}\\
\lambda b_{2}=\sqrt{k}(d, c)  \tag{8b}\\
\lambda c_{2}=\sqrt{k}\left(2 c b_{1}-a d_{1}\right)  \tag{8c}\\
-\lambda c \mu=k\left(d_{1} b_{1}^{2}\right)-\sqrt{k}\left(2 b_{1} d_{2}+b_{2} d_{1}\right) \mu \tag{8d}
\end{gather*}
$$

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$$
\begin{gather*}
0=2 b_{2} \mu^{2}+k\left[4 b_{1}^{2} b_{2}+2 b_{2} b_{1}^{2}+2 b_{1} d_{1} d_{2}+b_{2} d_{1}^{2}\right]-\sqrt{k}\left(c^{2}-d_{2}^{2}\right) \mu  \tag{8e}\\
0=2 a \mu^{2}+k\left[2 a b_{1}^{2}+a d_{1}^{2}\right]+\sqrt{k}\left(2 a d_{2} c\right) \mu  \tag{8f}\\
0=4 c \mu^{2}+k\left(c b_{1}^{2}\right)+3 \sqrt{k}\left(c b_{2}-a d_{2}\right) \mu  \tag{8g}\\
0=4 d_{2} \mu^{2}+k\left(2 b_{1} b_{2} d_{1}+b_{1}^{2} d_{2}\right)-3 \sqrt{k}\left(a c+b_{2} d_{2}\right)  \tag{8h}\\
\lambda a \mu=k\left[2 b_{1} b_{2}^{2}+2 b_{1} a^{2}+4 b_{1} b_{2}^{2}+b_{1} c^{2}+b_{1} d_{2}^{2}+2 b_{2} d_{1} d_{2}\right]-\sqrt{k}\left(d_{1} d_{2}\right) \mu  \tag{8i}\\
-\lambda b_{2} \mu=k\left[4 a b_{1} b_{2}+2 a d_{1} d_{2}\right]-\sqrt{k}\left(d_{1} c\right) \mu  \tag{8j}\\
-\lambda d_{2} \mu=k\left(2 b_{1} b_{2} c\right)+\sqrt{k}\left(a d_{1}-2 c b_{1}\right)  \tag{8k}\\
\lambda c \mu=k\left[a^{2} d_{1}+d_{1} b_{2}^{2}+2 b_{1} b_{2} d_{2}\right]+\sqrt{k}\left[2 b_{1} d_{2}+b_{2} d_{1}\right] \mu  \tag{8l}\\
0=-2 b_{2} \mu^{2}+k\left[2 b_{2} a^{2}+2 b_{2}^{3}+b_{2}\left(c^{2}+d_{2}^{2}\right)\right]-\sqrt{k}\left[d_{2}^{2}-c^{2}\right] \mu  \tag{8m}\\
0=-2 a \mu^{2}+k\left[2 a^{3}+2 a b_{2}^{2}+a\left(c^{2}+d_{2}^{2}\right)\right]-\sqrt{k}\left(2 d_{2} c\right) \mu  \tag{8n}\\
0=-4 c \mu^{2}+k\left[c\left(a^{2}+b_{2}^{2}\right)\right]-3 \sqrt{k}\left[-b_{2} c+a d_{2}\right] \mu  \tag{8o}\\
0=-4 d_{2} \mu^{2}+k\left[d_{2}\left(a^{2}+b_{2}^{2}\right)\right]+3 \sqrt{k}\left[a c+b_{2} d_{2}\right] \tag{8p}
\end{gather*}
$$

Since $u_{1}, v_{1}$ are fermionic, we must assume fermionic character for the coefficients $c$, $d_{1}, d_{2}$. Due to the fermionic character, it is important to note that $c^{2}=d_{1}^{2}=d_{2}^{2}=0$. Also note that $u_{0}, v_{0}$ are bosonic. Taking these into consideration, we obtain from (8)

$$
\begin{aligned}
a & =\frac{\left[\frac{\lambda}{b_{1}} \pm \sqrt{68 k}\right] \mu}{36 k} \\
b_{1} & = \pm \lambda /(2 \sqrt{k}) \\
b_{2} & =(\mu / \sqrt{k})\left[-\frac{1}{18} \pm\left(\lambda / 36 b_{1}\right) \sqrt{\frac{17}{k}}\right] \\
c & = \pm(\mu / 9 k)(A / B) \\
d_{1} & = \pm 9 \lambda B \\
d_{2} & = \pm(\mu / 9 k)(A / B) \mp 9 a(\sqrt{k} B \lambda) \\
\mu & = \pm\left(-\lambda^{2} / 4\right)^{1 / 2}
\end{aligned}
$$

and two constraint equations relating $a, \mu, \lambda, A, B$ and $k$

$$
\begin{aligned}
\left(\mu^{2} / 81 k^{2}\right)\left(A^{2} / B^{2}\right) & = \pm(\mu a \lambda / \sqrt{k}) \\
\text { and } \mu A^{2} & =\mp(\mu A) \pm 81 a \lambda\left(k^{3 / 2} B^{2}\right) \\
\text { where } A & =\left[(1 / 18)-\left(\lambda / 36 b_{1}\right)(17 / k)^{1 / 2}\right]^{1 / 2} \\
B & =\left[\frac{2}{k}\left\{19 /(18)^{2} \mp\left(5 \lambda / 162 b_{1}\right)(17 / k)^{1 / 2} \mp\left(\lambda / 36 b_{1}\right)^{2}(17 / k)\right\}\right]^{1 / 2}
\end{aligned}
$$

We thus obtain one type of exact solutions of (1) with one arbitrary parameter $\mu$ or $\lambda$.

We next proceed to obtain exact solutions of the coupled K-dV equations suggested by Hirota and Satsuma [7] that describes the interactions of two long waves with different dispersions.

These equations look like

$$
\begin{gather*}
u_{t}-a\left(u_{x x x}+6 u u_{x}\right)=2 b \Phi \Phi_{x}  \tag{9a}\\
\Phi_{t}+\Phi_{x x x}+3 u \Phi_{x}=0 \tag{9b}
\end{gather*}
$$

where $a, b$ are arbitrary constants.
We now look for travelling wave solutions of (9) that is, we assume

$$
\begin{gather*}
u(x, t)=u(x-w t)=u(\xi)  \tag{10a}\\
\Phi(x, t)=\Phi(x-w t)=\Phi(\xi) \tag{10b}
\end{gather*}
$$

where $w$ is velocity to be determined. Inserting (10) into (9), we get

$$
\begin{gather*}
-w u_{\xi}-a\left(u_{\xi \xi \xi}+6 u u_{\xi}\right)=2 b \Phi \Phi_{\xi}  \tag{11a}\\
-w \Phi_{\xi}+\Phi_{\xi \xi \xi}+3 u \Phi_{\xi}=0 . \tag{11b}
\end{gather*}
$$

To the equations 11(a), (b) we again make the ansatz

$$
\begin{align*}
& u=\sum_{i=0}^{m} a_{i}(\tanh \mu \xi)^{i}  \tag{12a}\\
& \Phi=\sum_{i=0}^{m} b_{i}(\tanh \mu \xi)^{i} \tag{12b}
\end{align*}
$$

where the integer $m, a_{i}, b_{i}(i=1, \ldots m)$ and $\mu$ are the parameters to be determined. The requirement that the highest power of the function $\tanh (\mu \xi)$ for the nonlinear

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term $u u_{\xi}$ (or $\Phi \Phi_{\xi}$ ) of (11a) and that for the derivative term $u_{\xi \xi \xi}$ must be equal gives the following relation

$$
2 m+1=m+3
$$

So here, $m=2$. For equation 11 (b) we also get $m=2$. Hence the equations (12a), (12b) now take the form

$$
\begin{align*}
& u=a_{0}+a_{1} \tanh \mu \xi+a_{2} \tanh ^{2} \mu \xi  \tag{13a}\\
& \Phi=b_{0}+b_{1} \tanh \mu \xi+b_{2} \tanh ^{2} \mu \xi \tag{13b}
\end{align*}
$$

where $a_{0}, b_{0}, a_{1}, b_{1}, a_{2}, b_{2}$ and $\mu$ are the parameters to be determined. Inserting now (13) in (11) and equating the same power of $\tanh (\mu \xi)$, we get twelve parametric equations where we get inconsistency in solving the parameters. But if we retain the highest power of $\tanh (\mu)$ and the parameters $a_{1}, b_{1}$ then (13) look like

$$
\begin{align*}
u & =a_{0}+a_{2} \tanh ^{2} \mu \xi  \tag{14a}\\
\Phi & =b_{0}+b_{2} \tanh ^{2} \mu \xi \tag{14b}
\end{align*}
$$

Inserting (14) in (11) and equating now the same power of $(\tanh \mu)$ we get following six parametric equations

$$
\begin{gather*}
-2 w a_{2}+16 a a_{2} \mu^{2}-12 a a_{0} a_{2}=4 b b_{0} b_{2}  \tag{15a}\\
-2 w b_{2}-16 b_{2} \mu+6 a_{0} b_{2}=0  \tag{15b}\\
-2 a_{2} w-40 a a_{2} \mu^{2}-12 a a_{2}^{2}+12 a a_{0} a_{2}=4 b\left(b_{2}^{2}-b_{0} b_{2}\right)  \tag{15c}\\
2 b_{2}+40 b_{2} \mu^{2}+6 a_{2} b_{2}-6 a_{0} b_{2}=0  \tag{15d}\\
24 a a_{2} \mu^{2}+12 a a_{2}^{2}=-4 b b_{2}^{2}  \tag{15e}\\
24 b_{2} \mu^{2}+6 a_{2} b_{2}=0 \tag{15f}
\end{gather*}
$$

On solving, we get

$$
\begin{aligned}
a_{0} & =\left(1+8 \mu^{2}\right) / 3 \\
a_{2} & =-4 \mu^{2} \\
b_{0} & =\frac{1}{b b_{2}}\left[2 \mu^{2}(2 a-1)-16 \mu^{3}+16 \mu^{4}(1+a)\right] \\
b_{2} & = \pm\left[\frac{-24 a \mu^{4}}{b}\right]^{1 / 2} \\
w & =\left(1-8 \mu+8 \mu^{2}\right) .
\end{aligned}
$$

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Thus we obtain one type of exact solutions of (9) with one arbitrary parameter $\mu$ (or $w$ ) which are different from those obtained by Hirota and Satsuma [7].

## 3. Conclusion

In our above computations we have shown that the method suggested by Huibin and Kelin $[8,9]$ is effective in obtaining exact solutions of non-linear partial differential equations. However, the question of stability of such solutions arises which is the matter of our present investigation and will be published elsewhere.

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U radu smo prikazali neke vrste točnih rješenja supersimetričnih nelinearnih Schrödingerovih jednadžbi i vezanih K-dV jednadžbi služeći se pretpostavkom o obliku rješenja u svakom pojedinom slučaju.

